## Introduction to Quantum Computing Day 3 – Qubo formulation of NP-Hard problems

Mengoni Riccardo, PhD

23 June 2021



#### Content

- QUANTUM ANNEALING
- NP-HARD PROBLEMS
- UNSUPERVISED LEARNING
  - K-MEANS CLUSTERING
  - QUANTUM ANNEALING FOR CLUSTERING
  - MINIMUM SPANNING TREE CLUSTERING
  - QUANTUM ANNEALING FOR MINIMUM SPANNING TREE
- SUPERVISED LEARNING
  - KERNEL METHODS AND SUPPORT VECTOR MACHINE
  - GRAPH EDIT DISTANCE
  - QUANTUM ANNEALING FOR GRAPH EDIT DISTANCE



# **0.** Quantum Annealing



Annealing in hardware. Once a native instance is formulated, it can be sent to the quantum annealing hardware for solution. The quantum annealing algorithm used by D-Wave incorporates the initial Hamiltonian

nitial Hamiltonian: 
$$\mathcal{H}_I = \sum_i \sigma_i^x$$
,

and the problem Hamiltonian

Final Hamiltonian: 
$$\mathcal{H}_{IM} = \sum_{i} h_i \sigma_i^z + \sum_{i < j} J_{ij} \sigma_i^z \sigma_j^z$$
,

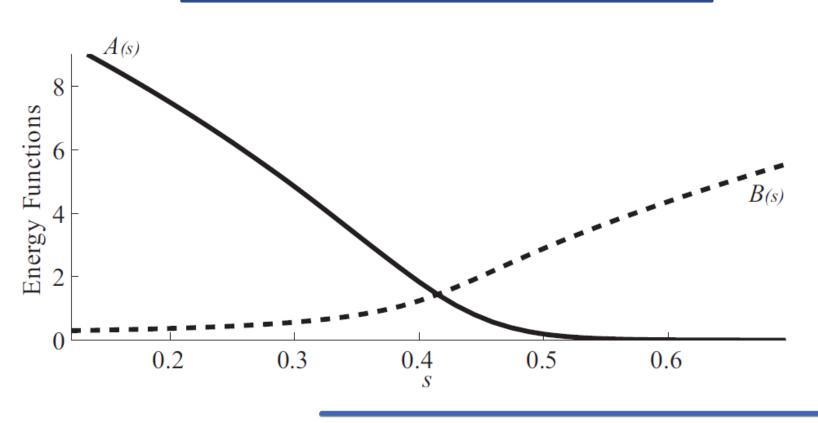
where  $h_i$  and  $J_{ij}$  are constrained to match the hardware working graph.



#### **Quantum Annealing**

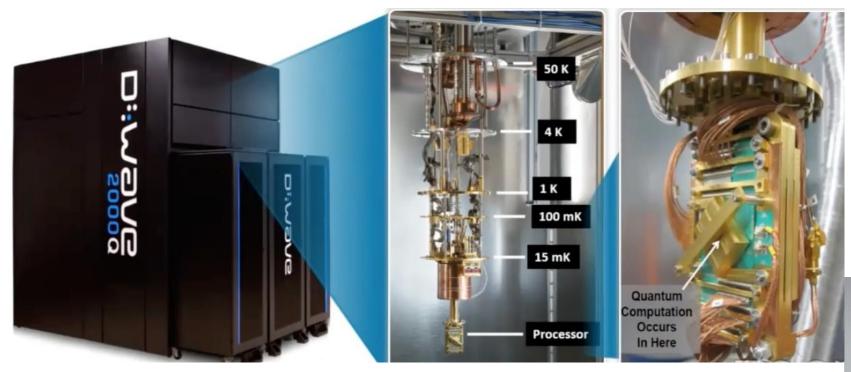
Thus D-Wave quantum annealers implement the following Hamiltonian:

$$\mathcal{H}(s) = A(s)\mathcal{H}_I + B(s)\mathcal{H}_{IM}.$$



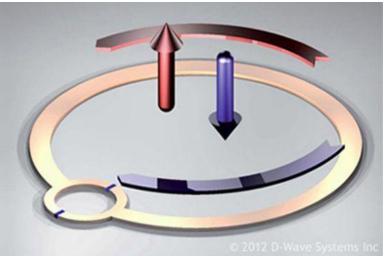


#### **D-Wave Quantum Annealer**



#### **Superconducting Circuits**

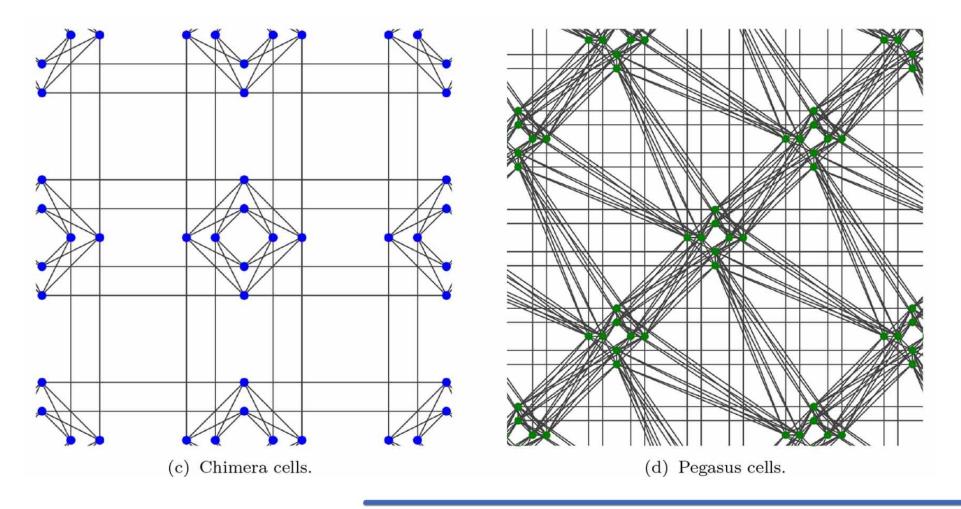
#### Two Annealers devices: - 2000 qubits - 5000 qubits





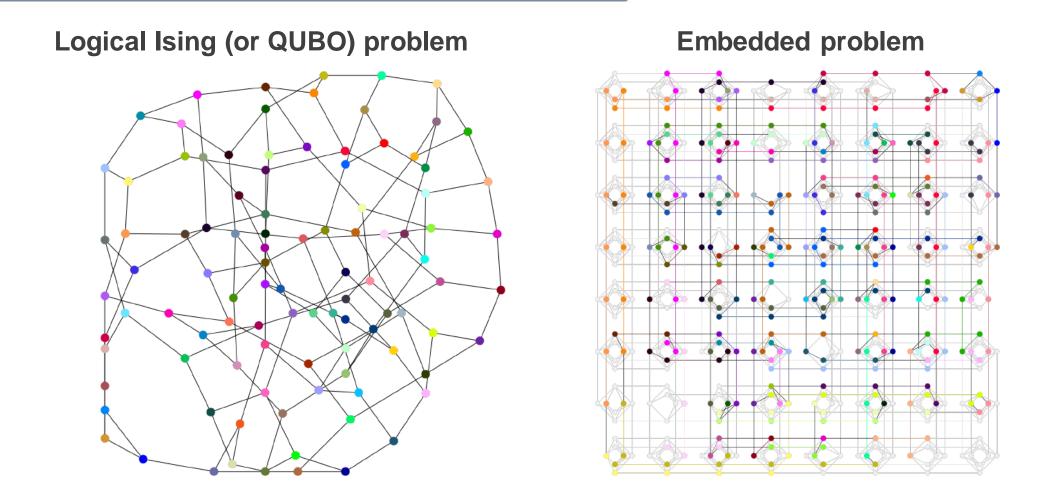
### **D-Wave Architecture**

The building blocks of the D-wave architecture are the **Chimera or Pegasus Graphs** 





## **Minor Embedding**

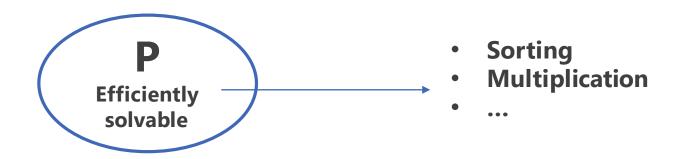


Minor-embedding a general graph G into a hardware working graph H.

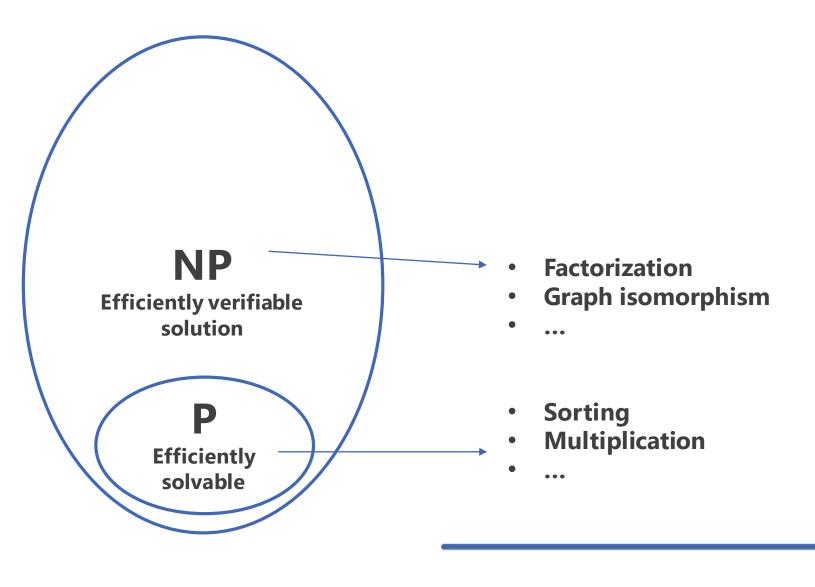


## **1. NP-Hard Problems**

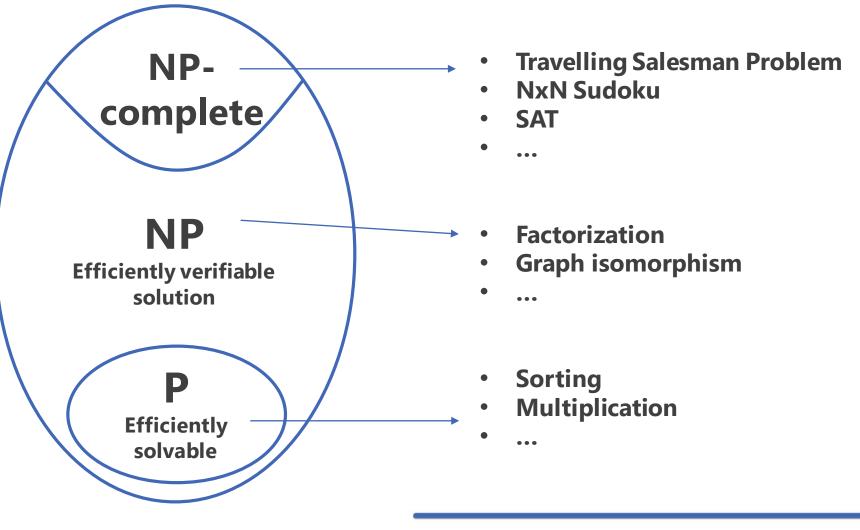




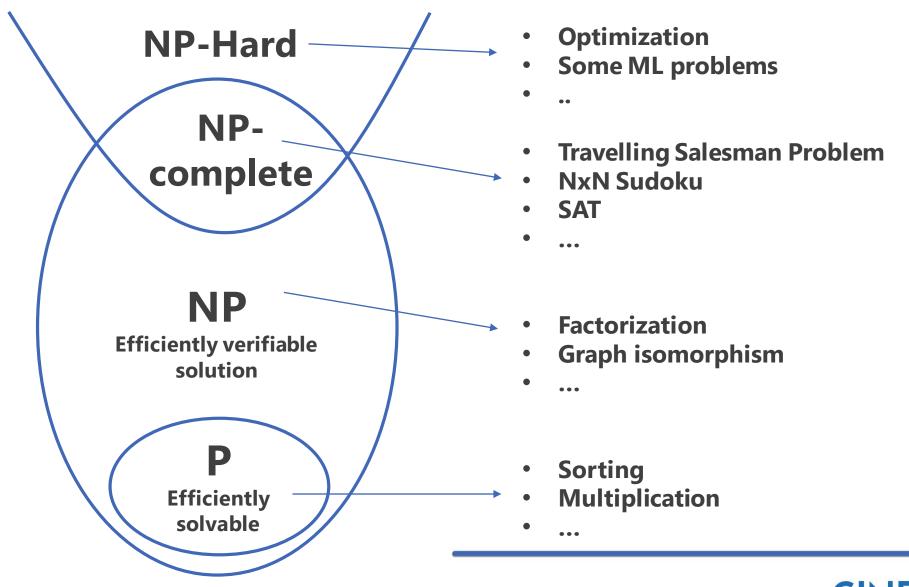




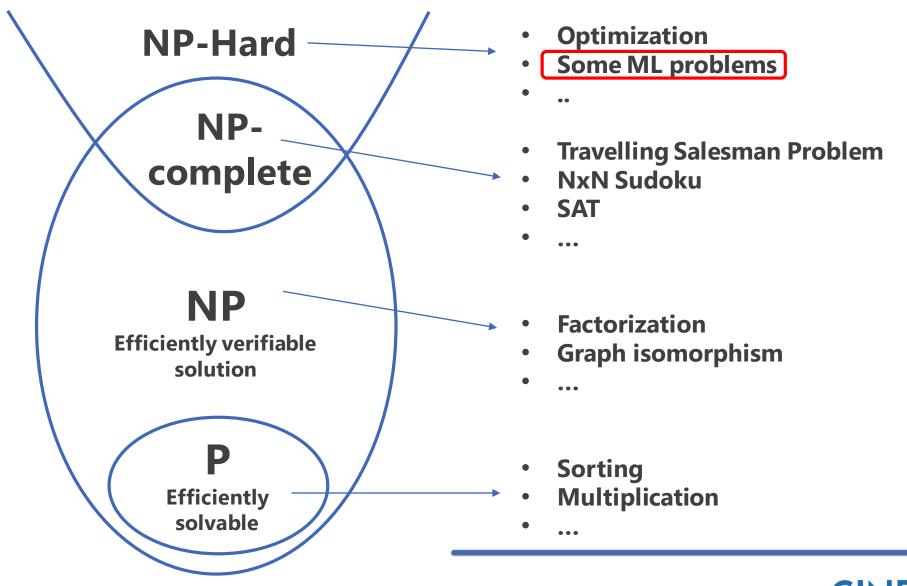












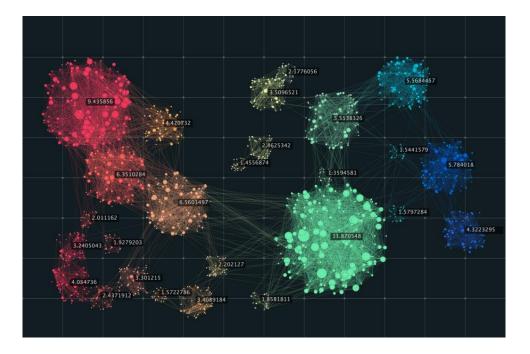


# 2. Unsupervised Learning



## **Unsupervised Learning**

The algorithm is provided with an **unlabelled dataset** with the goal of finding **patterns and structures without any prior experience of the problem**.



CINE

A standard examples of unsupervised learning task is **clustering** where **data-points** in the form of multidimensional vector are **assigned labels and grouped in such a way to minimize within-group distance** while **maximizing the margin between different classes.** 

# **K-means Clustering**



More in detail, consider an unlabelled dataset  $\mathcal{D}$  containing M feature vectors  $\vec{x} \in \mathbb{R}^N$ , the k-means algorithm aims to partition the dataset into  $k \leq M$  sets  $\mathbf{C} = \{C_1, C_2, ..., C_k\}$  in order to minimize the within-cluster variance. The objective function is the following

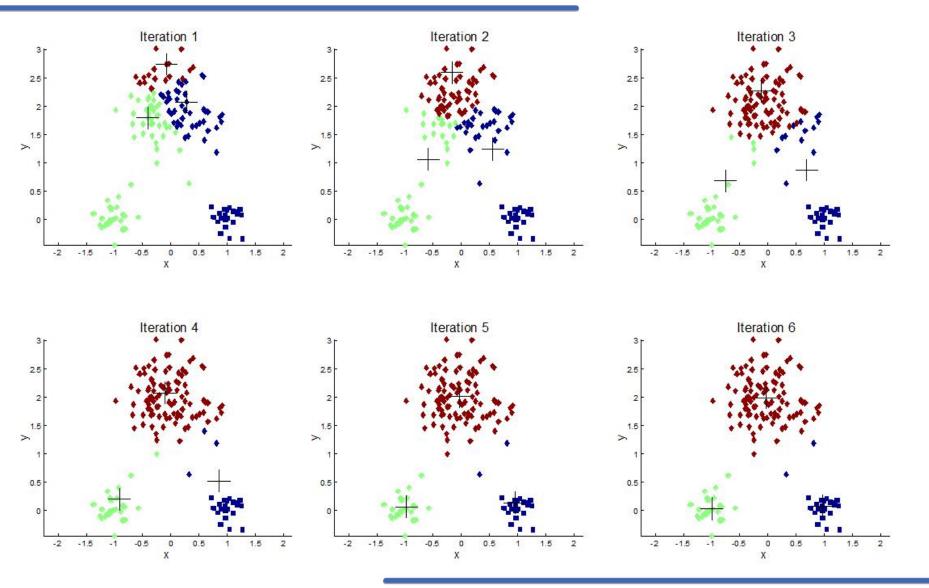
$$\underset{\mathbf{C}}{\operatorname{arg\,min}} \sum_{i=1}^{k} \sum_{\vec{x} \in C_{i}} \|\vec{x} - \vec{\mu}_{i}\|^{2}$$
(1.12)

where  $\vec{\mu}_i$  is the centroid or mean vector calculated among those points belonging to the same class  $C_i$ 

$$\vec{\mu}_{i} = \frac{1}{|C_{i}|} \sum_{\vec{x} \in C_{i}} \vec{x}.$$
(1.13)



#### **K-Means Clustering**





## **K-Means Clustering**

The algorithm at first randomly select k centroids and then follows an iterative procedure that alternates between two steps.

Repeated until convergence

- An **assignment step** where each vector is assigned to the cluster whose centroid has the least squared Euclidean distance.
- An updating step where it is calculated the new centroids of the vectors in the new clusters.

The algorithm **does not guarantee a convergence** to a global optimum **but** towards a **local minimum** Moreover the overall performance is largely affected by the initial choice of the centroids.

From the complexity point of view, finding the **optimal** solution for the k-means clustering problem is NP-hard in the Euclidean space



Let's try to formulate the clustering problem as a combinatorial optimization problem that we can address with Quantum Annealing



The idea is the following: consider a dataset  $\mathcal{D}$  containing M feature vectors  $\vec{x}_i \in \mathbb{R}^N$  that we want to partition into  $k \leq M$  sets  $\mathbf{C} = \{C_1, C_2, ..., C_K\}$  in order to minimize the within-cluster variance. We can start defining a binary variable  $z_i^{(k)}$  that is 1 only when the vector  $\vec{x}_i$  belongs to class  $C_i$ , in other words

$$z_i^{(k)} = \begin{cases} 1 \text{ iff } \vec{x}_i \in C_k \\ 0 \text{ iff } \vec{x}_i \notin C_k \end{cases}$$

Since every vector  $\vec{x_i}$  must be associated to a single class, this means that

$$\forall \vec{x}_i \quad \sum_{k=1}^K z_i^{(k)} = 1$$



$$z_i^{(k)} = \begin{cases} 1 \text{ iff } \vec{x}_i \in C_i \\ 0 \text{ iff } \vec{x}_i \notin C_i \end{cases} \quad \blacksquare \quad \forall \vec{x}_i \quad \sum_{k=1}^K z_i^{(k)} = 1 \end{cases}$$

This condition can be rephrased as an objective function as follows

$$f_1(z) = \sum_{i=1}^M \left(\sum_{k=1}^K z_i^{(k)} - 1\right)^2$$



Moreover, since we want the distance between vectors  $D_{i,j} = |\vec{x}_i - \vec{x}_j|$  to define the clusters, i.e we want to group together vectors that are closer, it is necessary to add the penalty term

$$f_2(z) = \sum_{k=1}^K \sum_{i \neq j} D_{i,j} z_i^{(k)} z_j^{(k)}$$

The **QUBO** associated to the clustering problem is therefore

$$O(z) = \lambda \sum_{i=1}^{M} \left( \sum_{k=1}^{K} z_i^{(k)} - 1 \right)^2 + \sum_{k=1}^{K} \sum_{i \neq j} D_{i,j} z_i^{(k)} z_j^{(k)}$$

where parameter  $\lambda$  was inserted to modulate the strength of **the first term**, which represent the **hard constraint** of the problem.



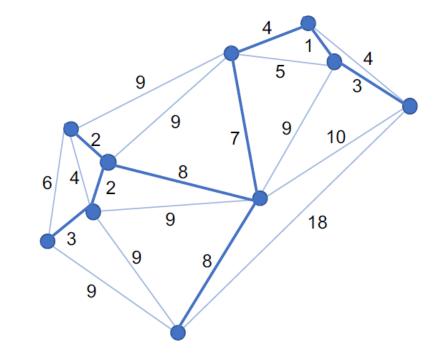
# **Minimum Spanning Tree Clustering**



#### Intro to the Minimum Spanning Tree problem

Consider a weighted graph G = (V, E, w) composed of a set V of n vertices, a set E of edges and a function  $w : E \to \mathbb{R}$  that associates a weight  $w_{v,v'}$  to each edge  $(v, v') \in E$ .

The Minimum Spanning Tree (MST) problem aims at finding a subgraph T of G such that: it does not contain cycles (i.e. T is a tree), it touches all the n vertices of G and it minimizes the sum overall edge weights.





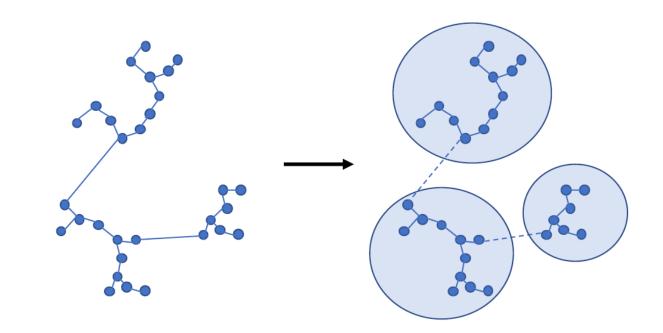
#### **Minimum Spanning Tree Clustering**

Given an unlabelled dataset  $\mathcal{D}$  containing *n* feature vectors  $\vec{x_i} \in \mathbb{R}^N$ , the MST based clustering algorithm considers the *n* points  $\vec{x_i}$  as nodes of a complete weighted graph *G*, where weights  $w_{i,j}$  represent the euclidean distance between any pair of points  $\vec{x_i}$  and  $\vec{x_j}$ .

$$w_{i,j} = d(\vec{x_i}, \vec{x_j})$$
 (1.14)

The algorithm computes the MST of the weighted graph G.

If the number of clusters k is known in advance, the algorithm sorts the edges of the MST in descending order and remove the (k-1) edges with heaviest weights





#### Delta Degree Minimum Spanning is NP-hard

In general, finding the MST of a given graph is not a hard task for a classical computer. In fact, given a graph where e is the number of edges and n is the number of vertices, the MST problem can be exactly solved in  $O(e \log n)$  time. However, with an additional constraint called  $\Delta$ -Degree constraint (i.e. each vertex in the MST must have degree less or equal than  $\Delta$ ), where  $2 \leq \Delta < n - 1$ , the problem becomes NP-hard and the corresponding decision problem NP-complete [9]. Finally, note that if the initial graph is complete, then a MST with  $\Delta$ -Degree constraint is ensured to exist.

➡

Let's try to formulate the Delta Degree Minimum Spanning Tree clustering problem as a combinatorial optimization problem that we can address with Quantum Annealing





Consider an ordering of the vertices, i.e. a bijective map that associates to each vertex only one indexed  $i \in \{1, 2, ..., n\}$  and vice versa. Define the binary variables  $x_{v,i}$  and  $y_{p,i}$  such that

 $x_{v,i} = \begin{cases} 1 \text{ iff } v \text{ is in position } i \\ 0 \text{ otherwise} \end{cases}$ 

and

$$y_{p,i} = \begin{cases} 1 \text{ iff } p \text{ is parent of vertex in position } i \\ 0 \text{ otherwise} \end{cases}$$

Because the root has no parent,  $y_{p,1}$  must be zero for every vertex. Moreover, since the root has been set from the beginning, it is already known that  $y_{p,2} = 1$  only when p is the root. Hence, we can safely restrict the variable  $y_{p,i}$  to the cases where  $p \in V$  and  $i \geq 3$ .



Let's now introduce the hard constraints these two variables have to satisfy in order to realize the MST. Since we considered a total ordering of the vertices, the following two QUBO terms should be considered:

$$\sum_{v \in V \setminus \{r\}} \left( \sum_{i=2}^n x_{v,i} - 1 \right)^2 + \sum_{i=2}^n \left( \sum_{v \in V \setminus \{r\}} x_{v,i} - 1 \right)^2$$

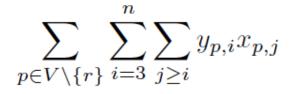
Where the first term ensures that only one i is associated to every v while the second term guarantees the converse.

Moreover, a necessary property to obtain a tree requires that each vertex has only one parent. Such property is expressed with the QUBO constraint

$$\sum_{i=3}^{n} \left( \sum_{p \in V} y_{p,i} - 1 \right)^2$$



Now we need to secure that, if p is in the parent of the vertex in position i, then p shouldn't be at greater or equal position. In QUBO form, such condition becomes



Finally, in order to make sure that <u>parents and children are indeed neighbours</u>, the following term that penalizes non-neighbours should be taken into account

$$\sum_{p \in V} \sum_{v \notin N(p), v \neq r} \sum_{i=3}^{n} x_{v,i} y_{p,i}$$

Note that this term does not give any contribution when the graph is complete, since all vertices are neighbours. Anyway we decided to insert this term form completeness, since it becomes relevant when the input graph is not complete.



The final QUBO form for the MST problem with  $\Delta$ -degree constrain is

$$A \sum_{v \in V \setminus \{r\}} \left( \sum_{i=2}^{n} x_{v,i} - 1 \right)^{2} + A \sum_{i=2}^{n} \left( \sum_{v \in V \setminus \{r\}} x_{v,i} - 1 \right)^{2} + A \sum_{i=3}^{n} \left( \sum_{p \in V} y_{p,i} - 1 \right)^{2} + A \sum_{p \in V \setminus \{r\}} \sum_{i=3}^{n} \sum_{j \ge i} y_{p,i} x_{p,j} + A \left( \sum_{p \in V} \sum_{v \notin N(p), v \neq r} \sum_{i=3}^{n} x_{v,i} y_{p,i} \right) + A \sum_{p \in V} \left( \sum_{i=3}^{n} y_{p,i} - \sum_{j=1}^{\Delta - 1} z_{p,j} \right)^{2} + B \left( \sum_{v \in N(r)} x_{v,2} w_{r,v} + \sum_{v \in V \setminus \{r\}} \sum_{p \in V} \sum_{i=3}^{n} y_{p,i} x_{v,i} w_{p,v} \right)$$
(7.7)

where the last term minimizes the sum of edge weights w.



#### Delta Degree constraint

In order to realize the  $\Delta$ -Degree constraint, a number  $\Delta - 1$  of binary slack variables  $z_{p,j}$  are introduced for each vertex. The QUBO term for this constrain is

$$\sum_{p \in V} \left( \sum_{i=3}^{n} y_{p,i} - \sum_{j=1}^{\Delta - 1} z_{p,j} \right)^2$$

#### **Parameter Setting**

As we can see from Eq. 7.7, parameter A have been introduced to define the strength of the hard constraints with respect to the cost term, multiplied instead by parameter B. In general, A >> B to ensure that the problem is well defined. In our case, the minimum value of A for which the problem is well defined is given by the relation

$$\frac{A}{B} > \max_{v,v' \in V} \{w_{v,v'}\}$$



# **3. Supervised Learning**

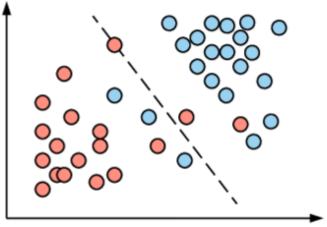


## **Supervised Learning**

It is given an **ensemble of labelled data points** usually called **training set**.

The learning algorithm has the task to induce a classifier from these labelled samples.

The classifier is a function that allocate labels to inputs, including those that are out of the training set which have never been previously analyzed by the algorithm.



**Supervised learning** 

- Classification
- Regression

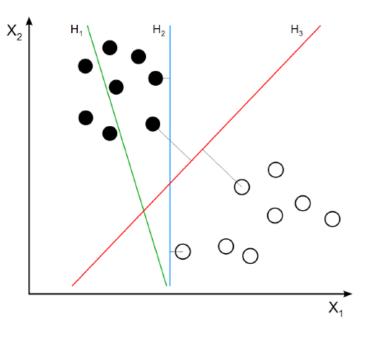


## **Kernel methods and SVMs**



### **Support Vector Machine (SVM)**

The task is to find a **hyperplane** that is the best discrimination between two class regions and serves as a decision boundary for future classification tasks.

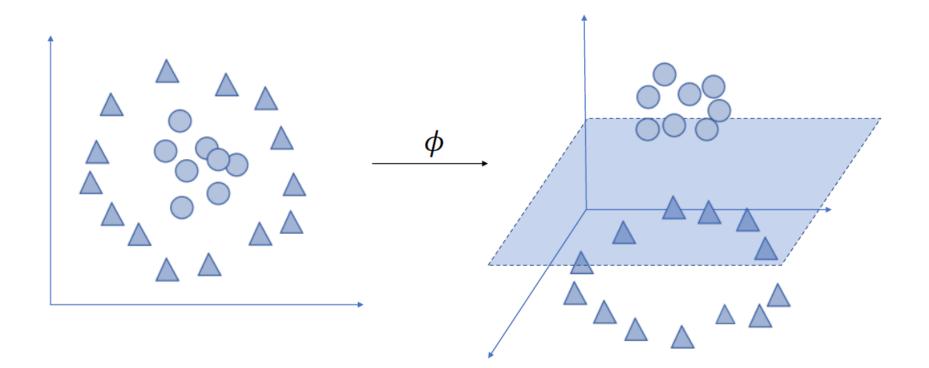


input: *M* training vectors  $\{(\vec{x}, y) \mid \vec{x} \in \mathbb{R}^N, y \in \{-1, +1\}\}$ 



### **Kernel Methods**

Kernel methods [115] are classification algorithms in ML that use a kernel function K in order to map data points, living in the input space V, to a higher dimensional feature space V', where separability between classes of data becomes clearer. Kernel methods avoid the calculation of points in the new coordinates but rather perform the so called kernel trick that allow to work in the feature space V' simply computing the kernel of pairs of data points [115] (see. Fig.1.2).





# **Graph Edit Distance**



The GED between two graphs is defined as

$$GED(g_1, g_2) = \min_{(e_1, \dots, e_k) \in \mathcal{P}(g_1, g_2)} \sum_{i=1}^k c(e_i)$$

where  $\mathcal{P}(g_1, g_2)$  denotes the set of edit paths transforming  $g_1$  into (a graph isomorphic to)  $g_2$  and  $c(e) \ge 0$  is the cost of an edit operation e.

Consider a kernel for SVM based on the GED

$$K(g_1,g_2)=\mathcal{F}(GED(g_1,g_2))$$

The problem of computing GED is NP-hard.



## **Quantum Annealing for GED**



#### **Quantum Annealing for Graph Edit Distance**

Let's try to calculate GED as the output of a combinatorial optimization problem that we can address with Quantum Annealing

Given two graphs  $G_1(V_1, E_1)$  and  $G_2(V_2, E_2)$  with the same number of nodes, we define a binary variable  $x_{v,i}$  as follows

$$x_{v,i} = \begin{cases} 1 & \text{if vertex } v \in V_2 \text{ gets mapped to vertex } i \in V_1 \\ 0 & \text{otherwise} \end{cases}$$



We are now introducing the initial Hamiltonian, i.e. the hard constraints, which must necessarily be satisfied in order to obtain a solution. To guarantee such bijective mapping it is necessary to formulate  $\mathcal{H}_A$  as follows:

$$\mathcal{H}_A = A \sum_{v} (1 - \sum_{i} x_{v,i})^2 + A \sum_{i} (1 - \sum_{v} x_{v,i})^2$$

As said before the number of nodes of the two graphs are the same, in this case  $\mathcal{H}_A$  must be zero in the optimal case. At this stage we also need a second term  $\mathcal{H}_B$  which penalize a bad mapping i.e. when two vertices i and j in  $G_1$  that are connected by and edge,  $(i, j) \in E_1$ , are mapped into vertices u and v in  $G_2$  which are not connected,  $(u, v) \notin E_2$  and vice versa.

$$\mathcal{H}_B = B \sum_{i,j \notin E_1} \sum_{u,v \in E_2} x_{u,i} x_{v,j} + B \sum_{i,j \in E_1} \sum_{u,v \notin E_2} x_{u,i} x_{v,j}$$



#### **Quantum Annealing for Graph Edit Distance**

The complete QUBO formulation is:

$$\mathcal{H}_{Qubo} = A \sum_{v} (1 - \sum_{i} x_{v,i})^{2} + A \sum_{i} (1 - \sum_{v} x_{v,i})^{2} + B \sum_{i,j \notin E_{1}} \sum_{u,v \notin E_{2}} x_{u,i} x_{v,j} + B \sum_{i,j \in E_{1}} \sum_{u,v \notin E_{2}} x_{u,i} x_{v,j}$$
(7.13)

So if the result of Eq. 7.13 is equal to 0, then the two graphs are isomorphic and their GED is 0. If the result is greater than 0, the minimum of  $\mathcal{H}_{Qubo}$  will be also the minimum distance between the two graphs, i.e.  $\mathcal{H}_{Qubo}$  will return the GED.

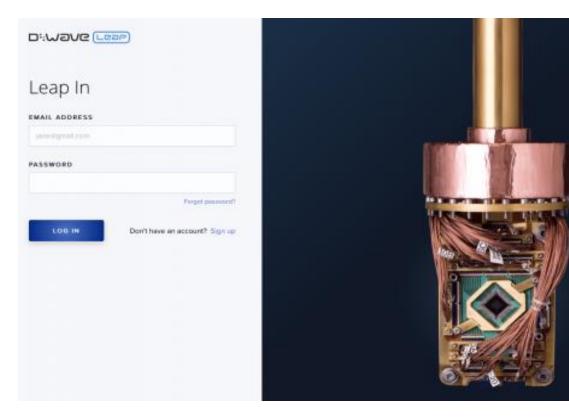
Since  $\mathcal{H}_A$  is a hard constraint, parameter A should be much higher than B if we want  $\mathcal{H}_A$  to be surely satisfied. However, since in the D-Wave quantum annealer all the QUBO coefficients (both linear,  $h_i$ , and quadratic,  $J_{ij}$ ) get normalized in the range [-1, 1], it is important to chose A and B in such a way that the normalized coefficients do not become too small. For this reason, a good choice for parameters A and B is the one where

$$\min_{i,j,k} \left( h_i^A, J_{jk}^A \right) \geq \max_{i,j,k} \left( h_i^B, J_{jk}^B \right)$$

where  $h_i^A$  and  $J_{jk}^A$  are respectively the linear and quadratic coefficients appearing in  $\mathcal{H}_A$  while  $h_i^B$  and  $J_{jk}^B$  are linear and quadratic coefficients of  $\mathcal{H}_B$ .



#### Try on the real D-Wave hardware



#### D-Wave access: https://cloud.dwavesys.com/leap/ (free 1 min / month)

| Solver Name                              | Status | Description   |
|--|--------|---|
| Hybrid                                   |        |   |
| hybrid_binary_quadratic_model_version2   | Online | Hybrid solver for general BQM problems, version 2.0 |
| hybrid_discrete_quadratic_model_version1 | Online | Hybrid solver for general DQM problems, version 1.0 |
| QPU                                      |        |   |
| Advantage_system1.1                      | Online | Advantage system                                    |
| DW_2000Q_6                               | Online | D-Wave 2000Q lower-noise<br>system                  |

#### **D-Wave Software Documentation:**

https://docs.ocean.dwavesys.com/en/stable/index.html



### **Quantum Computing @ CINECA**

CINECA: Italian HPC center CINECA Quantum Computing Lab:

- Research with Universities, Industries and QC startups
- Internship programs, Courses and Conference (HPCQC)

https://www.quantumcomputinglab.cineca.it



r.mengoni@cineca.it

